This quick guide is a summary of the complete installation manual. The manual contains safety warnings and other explanations which must be taken into account. The most recent versions of this guide and the installation manual are available at the "Downloads" section on Erreka's website.
http://www.erreka-automation.com
The options and functions described in this guide apply for the firmware version indicated on the circuit. The firmware, as part of a process of continuous improvement, is subject to new functionalities or upgrades being included as a result of new versions which are not necessarily compatible with previous ones. For this reason, some options or functions may differ or be unavailable if your firmware is older than shown in this guide.



## Unlocking

1 Turn the cover (1).
2 Insert the key (2) and turn it clockwise without forcing it (the cylinder will be pushed out a few millimetres by the spring).

3 Operate the handle (3) by turning it $180^{\circ}$ to the left. The gate can now be operated manually.
4 In order to extract the key and leave the operator unlocked, push inwards and turn anti-clockwise.

## Locking

1 Introduce the key (2) and turn clockwise without forcing it, until the cylinder is pushed out by the spring.

2 Operate the handle (3) by turning it $180^{\circ}$ to the right.
3 Push the key (2) in and turn it anti-clockwise (pushing it in completely in order to turn).

4 Turn the key (2) and remove the cover (1) until the cylinder is covered.
5 Move the gate manually until interlocked in the motor.


1 Press ENTER, with the display showing r5XX (r588, r588, r588, r588, etc).
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Interchange the cables connected to terminals G1 and G2 if turning direction is not as shown below, in accordance with [ IO I, [ 102 and the position of the operator (left or right):


P3: communication with inverter module
P4: encoder active

## D1 and D2:

| [L88 (static) | Gate closed |
| :---: | :---: |
| [L88 (flashing) | Gate closing |
| 0888 (static) | Gate open |
| 0988 (flashing) | Gate opening |
| P[88 (flashing) | Pedestrian door closing |
| 9088 (static) | Pedestrian door open |
| PO88 (flashing) | Pedestrian door opening |
| XX88 (countdown) | Gate on standby |
| PR88 (static) | Pause (operation not complete) |
| 5 LRP | STOP connector enabled |
| HERL | Excessive heating inverter module |
| [Bn | Communication failure with inverter module |

## D3 and D4 (during operation):

| 8888 | FT2 activated | 8888 | FT1 activated |
| :--- | :--- | :--- | :--- |
| 8888 | Flashing light | 8888 | green traffic light activated |
| 8888 | Internal FCC activated | 8888 | Internal FCA activated |
| 8888 | 2nd radio channel (or RSD) | 8888 | 1st channel radio signal |
| 8888 | External FCC activated | 8888 | External FCA activated |
| 8888 | ST2 activated | 8888 | ST1 activated |
| 8888 | LG activated | 8888 | red traffic light activated |

## D3 and D4 (in case of failure):

88[4 Opening safety device enabled
8855 Closing safety device enabled
88[9 Safety strip enabled
88E : Encoder motor shut down
88F I Force limit exceeded

## Total opening radio code programming P I (with RSD receiver only, [80 i)

If a receiver other than RSD is used, see the corresponding instructions.

Select the option [80 : (RSD receiver) before starting programming

Press ENTER, with the display showing r 5XX (r588, r588, r588, r588, etc).

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P274D

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P274G

## Pedestrian opening radio code programming, $P \mathcal{D}$ (with RSD receiver only, [80 I$)$

This procedure is the same as for total opening, but using parameter P Instead of P .

## Open/close programming (P3)

1 Press ENTER, with the display showing r5XX (r588, r598, r588, r588, etc).

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e Before programming, carry out an opening and closing movement at normal and slow speed in order to detect the corresponding currents (parameter R6XY).

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8 Start opening by pressing the transmitter, ST1 or ^.
9 Start slowdown by pressing the transmitter, ST1 or ^.
10 Wait for it to come to a stop at the end of travel.

11 Start closing by pressing the transmitter, ST1 or $\wedge$

12 Start slowdown by pressing the transmitter, ST1 or ^.
13 Wait for it to come to a stop at the end of travel.
\& Once programming is complete, the parameter R6XY is shown, indicating the suggested currents for normal speed ( X ) and fast speed ( $(\Psi)$. This can be modified if required.

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Pedestrian opening is programmed using the parameter F 3 (see "Complete programming chart").

## Clutch adjustment



1 Insert the Allen key (1) in the housing (2).
2 Turn the Allen key until the notches (3) and (4) face each other.

3 Insert a screwdriver in the notches (3) and (4) in order to immobilise the transmission and adjust the clutch by turning the key (1). Turning clockwise increases the power, whilst turning anticlockwise decreases it.
A Torque adjustment, respecting the maximum closing forces set out in Standard EN12453:2000. Make the measurements as described in Standard EN 12445:2000.

4 If the control panel has torque adjustment (PM), set it to the maximum.

| D1 | D2 | Parameter | D3 | D4 | Preset option | Options or values |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| [ | I | Motor turning direction and limit switches configuration | 0 | I | x |  |
|  |  |  | 0 | 2 |  |  |
|  | 3 | Type of gate | 0 | ? | X | Sliding gate |
|  | 4 | Opening safety device (photocell or strip) | 0 | 0 | X | Device not installed |
|  |  |  | 1 | 0 |  | Device without testing |
|  |  |  | 1 | 1 |  | Device with testing |
|  | 5 | Closing safety device (photocell or strip) <br> Closing photocell with [520 or [52 i, also prevents the start of gate opening | 0 | 0 | X | Device not installed |
|  |  |  | 1 | 0 |  | Device without testing |
|  |  |  | 1 | 1 |  | Device with testing |
|  |  |  | 2 | 0 |  | Device without testing |
|  |  |  | 2 | 1 |  | Device with testing |
|  | 7 | Encoder and limit switches (when using external limit switches, connect them to the corresponding terminals of the control board) | 0 | 0 |  | No encoder or limit switches |
|  |  |  | 0 | 2 | X | With internal limit switches |
|  |  |  | 0 | 4 |  | With encoder and internal limit switches |
|  |  |  | 0 | 6 |  | With external limit switches |
|  |  |  | 0 | 7 |  | With encoder and external limit switches |
|  | 8 | Radio receiver | 0 | 1 |  | RSD card (frame, not decoder) |
|  |  |  | 0 | 2 | X | Twin-channel decoder card |
|  | 9 | Safety strip type | 0 | 1 | X | Contact edge |
|  |  |  | 0 | 2 |  | Resistive edge |
|  | 8 | Slowdown | 0 | 0 |  | No slowdown |
|  |  |  | 0 | 1 | X | Slowdown in opening and closing |
|  |  |  | 0 | 2 |  | Slowdown in opening |
|  |  |  | 0 | 3 |  | Slowdown in closing |
| $p$ | 1 | Total opening radio code programming | $\bigcirc$ | ก |  |  |
|  | 2 | Pedestrian opening radio code programming | 0 | $\bigcirc$ |  |  |
|  | 3 | Gate open/close programming | $\bigcirc$ | $\square$ |  |  |
| F | । | Key command using ST1 and ST2 pushbuttons | 0 | 0 |  | ST1 and ST2 without effect, key commands are made by radio (channel 1: total opening-closing, channel 2: pedestrian opening-closing) |
|  |  |  | 0 | 1 | X | ST1 total opening-closing, ST2 pedestrian opening-closing |
|  |  |  | 0 | 2 |  | ST1 total opening, ST2 total closing |
|  |  |  | 0 | 3 |  | Dead-man mode |
|  |  |  | 0 | 4 |  | Dead-man mode in closing |
|  | 2 | Operation mode (step-by-step or automatic) and stand-by time (in seconds) in automatic mode | 0...5. | $0 . .9$ | 00 | 00: step-by-step mode <br> 0 I: automatic mode and stand-by time 1 second; ... <br> 59: automatic mode and stand-by time 59 sec.; <br> 1.0: 1 min. 0 sec.; ...; maximum 4 minutes |
|  | 3 | Pedestrian opening | $0 . .9$ | $0 . .9$ | 40 | 00: Pedestrian opening is not carried out <br> 0 I: 1\% of total opening <br> i己: $12 \%$ of total opening <br> 99: $99 \%$ of total opening (equivalent to 100\%) |
|  | 4 | Pedestrian closing mode (step-by-step or automatic) and stand-by time (in seconds) in automatic mode | 0...5. | $0 . .9$ | 00 | 00: step-by-step mode <br> 0 : : automatic mode and stand-by time 1 second; ... <br> 59: automatic mode and stand-by time 59 sec.; <br> 1.0: 1 min. 0 sec.; ...; maximum 4 minutes |


| 8 | 0 | Flashing light | 0 | 1 | X | No pre-warning, static output |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 0 | 2 |  | With pre-warning, static output |
|  | I | Garage light time | $0 . .5$. | $0 . .9$ | 03 | $59=59 \mathrm{sec} . ; 2.5=2 \mathrm{~min} .50 \mathrm{sec} .$, etc |
|  | 2 | Gate speed | 0 | 1... 9 | 03 | 0 : : minimum speed ( 40 Hz ); <br> 02: $45 \mathrm{~Hz}, 03: 50 \mathrm{~Hz}, 04: 55 \mathrm{~Hz}$, <br> 09: maximum speed ( 80 Hz ) |
|  | 3 | Slowdown speed | 0 | 1... 9 | 03 | 0 : : minimum speed ( 21 Hz ); 02: $22 \mathrm{~Hz}, \mathrm{O} 3: 23 \mathrm{~Hz}, 04: 24 \mathrm{~Hz}$, 09: maximum speed (29Hz) |
|  | 5 | Maximum trapping current (each value equivalent to 0.5 A ) <br> The digit D3 can be used to adjust current to normal speed <br> The digit D4 can be used to adjust current to slow speed | $0 . .9$ | $0 . .9$ | 00 | 00: disabled; <br> 0 : disabled at normal speed and 0.5 A at slow speed; <br> 10: 0.5A at normal speed and disabled at slow speed; ...; <br> 65: 3A at normal speed and 2.5A at slow speed;...; <br> 99: 4.5A at normal and slow speed |
|  | 7 | Closing photocell used during standby (in automatic mode only) | 0 | 0 |  | No effect |
|  |  |  | 0 | 1 |  | Immediate closing after crossing |
|  |  |  | 0 | 2 | X | Restarts standby time |
|  | 8 | Effect of pushbuttons (ST1, ST2) during stand-by time (in automatic mode only) | 0 | 0 |  | No effect |
|  |  |  | 0 | 1 |  | Cause immediate close |
|  |  |  | 0 | 2 | X | Restart stand-by time |
|  | 9 | Opening mode | 0 | 1 |  | Collective opening |
|  |  |  | 0 | 2 | X | Step-by-step alternative shutdown |
|  |  |  | 0 | 3 |  | Automatic alternative shutdown (only in automatic mode, $\mathrm{F} 2 \neq 00$ |
|  | b | Using the EPS1 card connector For parameters 8602 and 8603 , use the EPS1 card and bridge the network input cable connectors instead of disconnecting them from the network. | 0 | 0 | x | use for standard traffic light |
|  |  |  | 0 | 1 |  | use for brakes |
|  |  |  | 0 | 2 |  | NC contact with gate open (L1-COM) and gate closed (L2-COM) |
|  |  |  | 0 | 3 |  | impulse 1 second Open (L1-COM) when starting opening and Close (L2-COM) when starting closing. Allows another board to be activated |
|  | E | Special functions | 0 | 0 | X | no special function |
|  |  |  | 0 | 2 |  | industrial <br> (1.5s delay in shutdown and reversing) |
| n | 0 | Programming lock key Be sure to remember any key used, for future access to the programming | X | K | 0000 | The preset option is 00000 (no key). If any figure is changed, this is considered a key. Select the required key (starting with D1) using UP and DOWN. Press ESC to cancel or ENTER to confirm and move to D2, and so on. |
|  | 1 | Operations carried out (total counter) | X | X |  | Indicates the hundreds of cycles completed (for example, 58 indicates 6,800 cycles completed) |
|  | 2 | Operations carried out (partial counter, restarts with ST1 and ST2) | K | K |  | Indicates the hundreds of cycles completed (for example, 68 indicates 6,800 cycles completed) |
|  | 3 | Restore to default values, operation, radio and configuration | r | 5 |  | With the display showing n3r5 (with 3 flashing), press ENTER and birr will flash. Hold down ENTER until D1 shows b, restoring all programming menu values to default. |

