QUADRO COMANDO
CONTROL PANEL
CENTRALE DE COMMANDE
SELBSTÜBERWACHENDE STEUERUNG
CUADRO DE MANDOS
BEDIENINGSPANEEL


## INSTALLAZIONE VELOCE-QUICK INSTALLATION-INSTALLATION RAPIDE SCHNELLINSTALLATION-INSTALACION RAPIDA - SNELLE INSTALLATIE




MEMORIZZAZIONE RADIOCOMANDO MEMORIZING REMOTE CONTROLS MÉMORISATION RADIOCOMMANDE ABSPEICHERUNG DER FERNBEDIENUNG MEMORIZACION DEL RADIOMANDO MEMORISEREN AFSTANDSBEDIENINGD

$+\uparrow$ -
$-\downarrow$ -
$\mathrm{OK} \longmapsto-\square$


REGOLAZIONE FINECORSA,
ADJUSTING THE LIMIT SWITCHES,
H
REGLAGE DE LA FIN DE COURSE,
EINSTELLUNG DER ENDSCHALTER,
REGULACION DE LOS FINALES DE CARRERA,
REGELING EINDAANSLAGEN.

$\begin{array}{ll}+\uparrow & -\square \\ -\downarrow & -0 \\ 0 & -\square\end{array}$
ок $\downarrow$ -


APERTURA / OPENING / OUVERTURE ÖFFNUNG / APERTURA / OPENING:


ОК $\square$ Pr
CHIUSURA / CLOSING / FERMETURE SCHLIESSUNG / CIERRE / SLUITING:


REGOLAZIONE AUTOSET, ADJUSTING AUTOSET,
REGLAGE AUTOSET,
EINSTELLUNG AUTOSET,
REGULACION AUTOSET, REGELING AUTOSET.
$+\uparrow-0$

ок $\downarrow \square$


$$
\mathrm{OK} \square \square \times 2
$$

PRrRI

$\square$


$$
\ldots .3 \ldots .2 \ldots 1
$$



$$
\ldots .3 \ldots 2 \ldots 1
$$




Numero massimo di dispositivi verificati: 6 (ma non più di 4 per tipo), Maximum number of tested devices: 6 (but no more than 4 per type), Nombre maximum dispositif vérifiés: 6 (mais pas plus de 4 par type), Max. Anzahl der überprüften Geräte: 6 (jedoch nicht mehr als 4 je Typ), Número máximo dispositivos comprobados: 6 (pero no más de 4 por tipo), Maximumaantal "trusted devices": 6 (maar niet meer dan 4 per type).


Inversione del moto / Reversing motion / Inversion du mouvement
Umkehrung der Bewegung / Inversión del movimiento / Omkering van de beweging.:

## 0



Inversione del moto / Reversing motion / Inversion du mouvement
Umkehrung der Bewegung / Inversión del movimiento / Omkering van de beweging.:


## ACCESS TO MENUS Fig. 1





| DIAGNOSTICS and WARNINGS |  |  |
| :---: | :---: | :---: |
| DIAGNOSTICS CODE | DESCRIPTION | NOTES |
| ErOi | photocell test anomaly | check photocell connection and/or parameter/logic settings |
| ErO2 | safety edge test anomaly | check safety edge connection and/or parameter/logic settings |
| Er $\mathrm{HH}^{*}$ | hardware anomaly | check connections to motor |
| Er2H* | encoder anomaly | motor is moved manually and/or check encoder and relevant wiring |
| Er $3 H^{*}$ | amperostop anomaly | make sure movement is not hindered |
| Er 4 H* | thermal cutout anomaly | allow automated device to cool |
| Er5H* | communication anomaly | check connection with accessory devices and/or expansion boards or serial-connected devices |
| Era | buffer battery power anomaly | automated device running on battery power |
| * H = 0, $1, \ldots, 9, A, B, C, D, E, F$ |  |  |

## INSTALLER WARNINGS


#### Abstract

WARNING! Important safety instructions. Carefully read and comply with all the warnings and instructions that come with the product as incorrect installation can cause injury to people and animals and damage to property. The warnings and instructions give important information regarding safety, installation, use and maintenance. Keep hold of instructions so that you can attach them to the technical file and keep them handy for future reference.


## GENERAL SAFETY

This product has been designed and built solely for the purpose indicated herein. Uses other than those indicated herein might cause damage to the product and create a hazard.
-The units making up the machine and its installation must meet the requirements of the following European Directives, where applicable: 2004/108/EC, 2006/95/ EC, 2006/42/EC, 89/106/EC, 99/05/EC and later amendments. For all countries outside the EEC, it is advisable to comply with the standards mentioned, in addition to any national standards in force, to achieve a good level of safety. The Manufacturer of this product (hereinafter referred to as the "Firm") disclaims all responsibility resulting from improper use or any use other than that for which the product has been designed, as indicated herein, as well as for failure to apply Good Practice in the construction of entry systems (doors, gates, etc.) and for deformation that could occur during use.

- Installation must be carried out by qualified personnel (professional installer, according to EN 12635), in compliance with Good Practice and current code.
Before commencing installation, check the product for damage.
-Before installing the product, make all structural changes required to produce safety gaps and to provide protection from or isolate all crushing, shearing and dragging hazard areas and danger zones in general. Check that the existing structure meets the necessary strength and stability requirements.
-The Firm is not responsible for failure to apply Good Practice in the construction and maintenance of the doors, gates, etc. to be motorized, or for deformation that might occur during use.
-Make sure the stated temperature range is compatible with the site in which the automated system is due to be installed.
Do not installthis product in an explosive atmosphere: the presence offlammable fumes or gas constitutes a serious safety hazard.
-Disconnect the electricity supply before performing any work on the system. Also disconnect buffer batteries, if any are connected.
Before connecting the power supply, make sure the product's ratings match the mains ratings and that a suitable residual current circuit breaker and overcurrent protection device have been installed upline from the electrical system. Have the automated system's mains power supply fitted with a switch or omnipolar thermal-magnetic circuit breaker with a contact separation that meets code requirements.
-Make sure that upline from the mains power supply there is a residual current circuit breaker that trips at no more than 0.03 A as well as any other equipment required by code.
-Make sure the earth system has been installed correctly: earth all the metal parts belonging to the entry system (doors, gates, etc.) and all parts of the system featuring an earth terminal.
Installation must be carried out using safety devices and controls that meet standards EN 12978 and EN 12453.
-Impact forces can be reduced by using deformable edges.
-In the event impact forces exceed the values laid down by the relevant standards, apply electro-sensitive or pressure-sensitive devices.
- Apply all safety devices (photocells, safety edges, etc.) required to keep the area free of impact, crushing, dragging and shearing hazards. Bear in mind the standards and directives in force, Good Practice criteria, intended use, the installation environment, the operating logic of the system and forces generated by the automated system.
- Apply all signs required by current code to identify hazardous areas (residual risks). All installations must be visibly identified in compliance with the provisions of standard EN 13241-1.
-This product cannot be installed on leaves incorporating doors (unless the motor can be activated only when the door is closed).
-If the automated system is installed at a height of less than 2.5 m or is accessible, the electrical and mechanical parts must be suitably protected.
-Install any fixed controls in a position where they will not cause a hazard, away from moving parts. More specifically, hold-to-run controls must be positioned within direct sight of the part being controlled and, unless they are key operated, must be installed at a height of at least 1.5 m and in a place where they cannot be reached by the public.
Apply at least one warning light (flashing light) in a visible position, and also attach a Warning sign to the structure.
-Attach a label near the operating device, in a permanent fashion, with information on how to operate the automated system's manual release.
-Make sure that, during operation, mechanical risks are avoided or relevant protective measures taken and, more specifically, that nothing can be banged, crushed, caught or cut between the part being operated and surrounding parts.
-Once installation is complete, make sure the motor automation settings are correct and that the safety and release systems are working properly.
Only use original spare parts for any maintenance or repair work. The Firm disclaims all responsibility for the correct operation and safety of the automated system if parts from other manufacturers are used.
-Do not make any modifications to the automated system's components unless explicitly authorized by the Firm.
-Instruct the system's user on what residual risks may be encountered, on the control systems that have been applied and on how to open the system manually in an emergency. give the user guide to the end user.
Dispose of packaging materials (plastic, cardboard, polystyrene, etc.) in accordance with the provisions of the laws in force. Keep nylon bags and polystyrene out of reach of children.


## WIRING

WARNING! For connection to the mains power supply, use: a multicore cable with a cross-sectional area of at least $5 \times 1.5 \mathrm{~mm}^{2}$ or $4 \times 1.5 \mathrm{~mm}^{2}$ when dealing with three-phase power supplies or $3 \times 1.5 \mathrm{~mm}^{2}$ for single-phase supplies (by way of example, type H05 VV-F cable can be used with a cross-sectional area of $4 \times 1.5 \mathrm{~mm}^{2}$ ). To connect auxiliary equipment, use wires with a cross-sectional area of at least $0.5 \mathrm{~mm}^{2}$.

- Only use pushbuttons with a capacity of 10A-250V or more.
- Wires must be secured with additional fastening near the terminals (for example, using cable clamps) in order to keep live parts well separated from safety extra low voltage parts.
During installation, the power cable must be stripped to allow the earth wire to be connected to the relevant terminal, while leaving the live wires as short as possible. The earth wire must be the last to be pulled taut in the event the cable's fastening device comes loose.
WARNING! safety extra low voltage wires must be kept physically separate from low voltage wires.
Only qualified personnel (professional installer) should be allowed to access live parts.


## CHECKING THE AUTOMATED SYSTEM AND MAINTENANCE

Before the automated system is finally put into operation, and during maintenance work, perform the following checks meticulously:
-Make sure all components are fastened securely.
-Check starting and stopping operations in the case of manual control.
-Check the logic for normal or personalized operation.
-For sliding gates only: check that the rack and pinion mesh correctly with 2 mm of play; keep the track the gate slides on clean and free of debris at all times. -Check that all safety devices (photocells, safety edges, etc.) are working properly and that the anti-crush safety device is set correctly, making sure that the force of impact measured at the points provided for by standard EN 12445 is lower than the value laid down by standard EN 12453.
-Make sure that the emergency operation works, where this feature is provided.
Check opening and closing operations with the control devices applied.
-Check that electrical connections and cabling are intact, making extra sure that insulating sheaths and cable glands are undamaged.
-While performing maintenance, clean the photocells' optics.
-When the automated system is out of service for any length of time, activate the emergency release (see"EMERGENCY OPERATION" section) so that the operated part is made idle, thus allowing the gate to be opened and closed manually. -If the power cord is damaged, it must be replaced by the manufacturer or their technical assistance department or other such qualified person to avoid any risk

## SCRAPPING

Materials must be disposed of in accordance with the regulations in force. There are no particular hazards or risks involved in scrapping the automated system. For the purpose of recycling, it is best to separate dismantled parts into like materials (electrical parts - copper - aluminium - plastic - etc.).

## DISMANTLING

If the automated system is being dismantled in order to be reassembled at another site, you are required to:
-Cut off the power and disconnect the whole electrical system.
-Remove the actuator from the base it is mounted on.
-Remove all the installation's components.
-See to the replacement of any components that cannot be removed or happen to be damaged.

Anything that is not explicitly provided for in the installation manual is not allowed. The operator's proper operation can only be guaranteed if the information given is complied with. The Firm shall not be answerable for damage caused by failure to comply with the instructions featured herein.
While we will not alter the product's essential features, the Firm reserves the right, at any time, to make those changes deemed opportune to improve the product from a technical, design or commercial point of view, and will not be required to update this publication accordingly.

## 2) GENERAL OUTLINE

The HIDE SW control panel is supplied by the manufacturer with standard setting Any alteration must be set by means of the incorporated display programmer or by means of universal palmtop programmer. The Control unit completely supports the EELINK protocol.
Its main characteristics are:

- Control of two HIDE SW motors
- Electronic torque control with obstacle detection

Encoder control inputs

- Separate inputs for safety devices

Incorporated rolling-code radio receiver with transmitter cloning
The board is provided with a terminal board which can be pulled out for easier maintenance or replacement. The board is supplied with a series of pre-wired jumpers to facilitate the installer's work.
The jumpers relate to the following terminals: 15-17,15-18, 15-27. If the abovementioned terminals are in use, remove their respective jumpers.

WARNING: the motor comes in the CLOSED position.
DO NOT ALTER THE POSITION OF THE MOTOR UNTIL INSTALLATION HAS BEEN COMPLETED.
Install the motor with the leaf closed, then remove the seal.

## CHECK

TheHIDESW panel carries outa control (check) onthestarting relays and safetydevices (photocells) before carrying out each opening and closing cycle.
In case of malfunction, check the devices connected for regular operation and check the wiring.
3) TECHNICAL DATA

| MOTOR |  |
| :---: | :---: |
| Power supply | $230 \mathrm{~V} \sim \pm 10 \% 50 \mathrm{~Hz}$ * |
| Mains/low voltage insulation | $>2 \mathrm{MOhm} \mathrm{500V}=-$ |
| Power input | 40W |
| Max. torque | 345 Nm |
| Speed | 7.5\% |
| Protection rating | IP 45 |
| Max. leaf length | 2 m |
| Max. leaf weight | 150 Kg |
| Leaf surface area | $3 \mathrm{sq} \mathrm{m} \mathrm{/} 5 \mathrm{sq} \mathrm{m}$ |
| Operator weight | 8 kg ( $\approx 80 \mathrm{~N}$ ) |
| Use | residential |
| Max. opening angle | $110^{\circ}$ |
| Working temperature | $-20 /+60^{\circ} \mathrm{C}$ |
| Wind resistance | class 2 / class 1 |
| CONTROL UNIT |  |
| Thermal protection | Software |
| Dielectric strength | mains/low voltage 3750V ~ per 1 minute |
| Motor output current | 7.5A+7.5A max |
| Motor relay commutation current | 10A |
| Maximum motor power | 200W + 200W (24V =--) |
| Supply to accessories | 24V~ (180mA max absorption) <br> 24V~safe (180mA max absorption) |
| Gate-open warning light | Contatto N.O. (24V~/1A max) |
| Blinker | $24 \mathrm{~V} \sim 25 \mathrm{~W}$ max |
| Dimensions | see Fig. C |
| Fuses | see Fig. E |
| $\mathrm{N}^{\circ}$ of combinations | 4 billion |
| Max. $\mathrm{n}^{\circ}$ of remotes that can be memorized | 63 |

(* other voltages available on request)

## WARNING:

- the actuator has been designed to be integrated into the gate's structure. - do not make holes in the structure anywhere around the space housing the actuator as this could compromise the machine's characteristics.

Usable transmitter versions:
All ROLLING CODE transmitters compatible with


## 4) TUBE ARRANGEMENT Fig. A

## 5) ASSEMBLING THE MOTOR FIG.B <br> AWARNING:

- line the seal up with the leaf in the closed position (Fig.B Ref. 1)
- Remove the seal (Fig.B Ref. 2)
- Power the motor only once it has been coupled with the leaf and hinges.

6) CONNECTION OF 1 PAIR OF PHOTOCELLS AND 1 PAIR OF SAFETY EDGES, UNTESTED Fig. F

## 7) TERMINAL BOARD CONNECTIONS Fig. E

WARNING - During the wiring and installation operations, refer to the current standards as well as principles of good technical practice.
Wires powered at different voltages must be physically separated, or suitably insulated with at least 1 mm extra insulation. The wires must be clamped by an extra fastener near the terminals, for example by bands.
All the connection cables must be kept at an adequate distance from the dis sipator.

| TERMINAL | DESCRIPTION |
| :---: | :---: |
| L-N | Single-phase mains power supply $230 \mathrm{~V} \sim \pm 10 \%$ |
| 3-4-5 | Connection to motor 1: <br> 3 motor 1 cable 1 <br> 4 motor 1 cable 2 <br> 5 motor 1 cable 3 |
| 6-7-8 | Connection to motor 2: <br> 6 motor 2 cable 2 <br> 7 motor 2 cable 1 <br> 8 motor 2 cable 3 |
| 9-10 | Connection to blinker (24V~ 25W max) |
| 11-12 | Output 24V $\sim 180 \mathrm{~mA}$ max - supply to photocells or other devices. <br> 11 motore 1-2 cable 5 <br> 12 motore 1-2 cable 6 |
| 13-14 | Output 24V $\sim$ V safe 180 mA max-supply to photocell transmitters with checking function (Fig. J). |
| 15-16 | START pushbutton (N.O.). |
| 15-17 | STOP pushbutton (N.C.). If not used, leave the bridge 15-17 connected. |
| 15-18 | PHOTOCELL input (N.C.). If not used, leave the bridge 15-18 connected. |
| 19 | FAULT input (N.O.). Input for photocells provided with checking N.O. contact (Fig. J). |
| 15-20 | PEDESTRIAN pushbutton input (N.O.). Activation is carried out by motor 2; if the opening cycle has started (not from pedestrian function), the pedestrian command has no effect. |
| 21-22 | Outputforgate-open warning lightoutput(N.O. contact(24V~/1A max)) or alternatively 2nd radio channel (Fig. E rif. 1). |
| 23 | Not used |
| 24 | Limit switch common (Motors 1 and 2 cable 4) |
| 15-25 | OPEN button (N.O.). |
| 15-26 | CLOSE button (N.O.) |
| 15-27 | EDGE INPUT (N.C.) If not used, leave the bridge 15-27 connected. |
| 28 | EDGE FAULT (N.O.) |

## 8) MEMORIZING REMOTE CONTROLS Fig. G

## 9) LIMIT SWITCH SETTING MENU Fig. H

If the leaf moves in the wrong direction, adjust the "motor reverse" logic accordingly (+ opening / - closing).
NOTE: these manoeuvres are carried out in hold-to-run mode at reduced speed and without safety device activation. If the " 1 not on" logic is set, only the messages relating to motor 2 will be displayed ("oPח己"e"cLпㄹ").

## 10) AUTOSET MENU Fig. I

Allows you to automatically set the Motor torque.
WARNING!!The autosetting operation is only to be carried out after checking the exact leaf movement (opening/closing) and correct limit switch activation.
You are advised to carry out an autosetting procedure each time you modify the slow-down speed or space.
WARNING! During the autoset phase, the obstacle detection function is not active, therefore the installer must control the automation movement and prevent persons and things from approaching or standing within the automation working range.
In the case where buffer batteries are used, autosetting must be carried out with the control panel supplied by mains power voltage.

WARNING: The torque values fixed by means of the autoset procedure ! refer to the slow-down speed fixed during the same procedure. If the slow-down speed or space is modified, a new autosetting manoeuvre must be carried out.
be carried out.
WARNING: Check that the impact force value measured at the
points established by the EN 12445 standard is lower than that specified in the EN 12453 standard.
Incorrect sensitivity setting can cause injuries to persons or animals, or damage to things.

## INSTALLATION MANUAL

11) SAFETY DEVICES

Note: only use receiving safety devices with free changeover contact.
11.1) TESTED DEVICES Fig. J

## 12) CLOSING LIMIT SWITCH PRESSURE Fig. K

## 13) CONNECTION WITH EXPANSION BOARDS AND UNIVERSAL HANDHELD

 PROGRAMMER Fig. LRefer to specific manual.

## ACCES TO MENU: Fig. 1

PARAMETERS MENU (PRrRT)
(TABLE "A" PARAMETERS)
LOGIC MENU (LoĹ ic)
(TABLE "B" LOGIC)
RADIO MENU (rRd o)
$\left.\begin{array}{|c|l|}\hline \text { Logic } & \text { Description } \\ \hline \text { Rdd StRrt } & \begin{array}{l}\text { Add Start Key } \\ \text { associates the desired key with the Start command }\end{array} \\ \hline \text { Rdd 2ch } & \begin{array}{l}\text { Add 2ch Key } \\ \text { associates the desired key with the 2nd radio channel command }\end{array} \\ \hline \text { rERd } & \begin{array}{l}\text { Read } \\ \text { Checks a key of a receiver and, if memorized, returns the } \\ \text { number of the receiver in the memory location (from 01 to } \\ \text { 63) and number of the key (T1-T2-T3 or T4). }\end{array} \\ \hline \text { ErR5E 54 } & \begin{array}{l}\text { Erase List } \\ \text { WARNING! Erases all memorized remote controls from } \\ \text { Cod rHe receiver's memory. }\end{array} \\ \hline \text { Lit } & \begin{array}{l}\text { Read receiver code } \\ \text { Displays receiver code required for cloning remote controls. }\end{array} \\ \hline \text { ON = Enables remote programming of cards via a previously } \\ \text { memorized W LINK transmitter. It remains enabled for } \\ \text { 3 minutes from the time the W LINK remote control is } \\ \text { last pressed. }\end{array}\right\}$

## - IMPORTANT NOTE: THE FIRST TRANSMITTER MEMORIZED MUST BE

 IDENTIFIED BY ATTACHING THE KEY LABEL (MASTER).In the event of manual programming, the first transmitter assigns the RECEIVER'S KEY CODE: this code is required to subsequently clone the radio transmitters. The Clonix built-in on-board receiver also has a number of important advanced features:

- Cloning of master transmitter (rolling code or fixed code)
- Cloning to replace transmitters already entered in receiver
- Transmitter database management
- Receiver community management

To use these advanced features, refer to the universal handheld programmer's instructions and to the CLONIX Programming Guide, which come with the universal handheld programmer device.

LANGUAGE MENU (LRnELiREE)
Used to set the programmer's language on the display.
DEFAULT MENU (dEFRiLL )
Restores the controller's default factory settings.
AUTOSET MENU (Ruto oset)
See Fig. I and "Autoset Men".
LIMIT SWITCH SETTING MENU (rE[ $F_{c}$ )
See Fig. H and "Limit Switch Setting Menu"

## MONITORING

The torque parameter defines the maximum acceptable difference between the instant torque and the expected instant torque, i.e. it indicates sensitivity to the obstruction. The lesser the torque parameter, the greater the sensitivity to the obstruction (Torque $1=$ maximum sensitivity).
14) ADJUSTING PROCEDURE

- Before switching on, check electrical connections.
- Set the following parameters: Automatic Closing Time, Opening and closing delay times, speed and Slow-down Distance.
- Set all the logics.
- Carry out the autoset procedure.

After completing the autoset procedure, the Motor fast time and the Torque can be manually adjusted.
WARNING! Any incorrect setting can cause injuries to persons and animals or damage to things.
WARNING:check that the impact force value measured at the points established by the EN 12445 standard is lower than that specified in the EN 12453 standard.
To obtain a better result, it is advisable to carry out the autoset procedure and the fast time setting with the motors at rest (i.e. not overheated by a considerable number of consecutive manoeuvres).

TABLE "A" - PARAMETERS MENU - (PRrRח)

| Logic | min. | max. | Default | Personal | Definition | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| tcR | 0 | 120 | 40 |  | Automatic Closing Time | Set the numerical value of the automatic closing time from 0 to 120 seconds. |
| oPEn dELRy $t$ IRE | 0,0 | 10,0 | 3 |  | Opening delay time | Set the opening delay time for motor 1 relative to motor 2 , between 0,0 and 10,0 seconds. Adjust the time lag so that the minimum distance between the leaves, when both are moving, is 50 cm . |
| $\begin{gathered} \text { cL5 dELRY } \\ \text { L ME } \end{gathered}$ | 0,0 | 60,0 | 3 |  | Closing delay time | Set the closing delay time for motor 2 relative to motor 1 , between 0,0 and 60,0 seconds. Adjust the time lag so that the minimum distance between the leaves, when both are moving, is 50 cm . |
| not 1 tor 9UE | 1 | 99 | 50 |  | Motor 1 torque | Set the numerical value of the motor 1 torque between $1 \%$ and $99 \%$. This parameter denotes sensitivity to the obstacle (couple=1 maximum sensitivity). |
| not 2 tor 9 UE | 1 | 99 | 50 |  | Motor 2 torque | Set the numerical value of the motor 1 torque between $1 \%$ and $99 \%$. This parameter denotes sensitivity to the obstacle (couple=1 maximum sensitivity). |
| SLou 5PEEd | 15 | 50 | 15 |  | Slow-down speed | Sets the slow-down speed percentage between $15 \%$ and $50 \%$ of normal speed. |
| op 5PEEd | 50 | 99 | 99 |  | Speed during opening | Sets the running speed that the motor must reach during opening, as a percentage of the maximum speed the actuator can reach. If this parameter is edited, the autoset opening and closing cycle will need to be performed again. |
| cL 5PEEd | 50 | 99 | 99 |  | Speed during closing | Sets the running speed that the motor must reach during closing, as a percentage of the maximum speed the actuator can reach. If this parameter is edited, the autoset opening and closing cycle will need to be performed again. |
| d ${ }^{\text {St. SLoud }}$ | 5 | 50 | 5 |  | Slow-down space | Set the slow-down percentage between $5 \%$ and $59 \%$ with respect to the complete manoeuvre. |
| RP. PRre. | 10 | 99 | 40 |  | Pedestrian opening | Set the partial opening percentage for motor 2. |

TABLE"B"- LOGIC MENU - (LoLic)

| Logic | Default | Definition | $\begin{gathered} \text { Cross out } \\ \text { setting } \\ \text { used } \end{gathered}$ | Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| tcR | OFF | Automatic Closing Time | ON | Activates automatic closing |  |  |  |
|  |  |  | OFF | Excludes automatic closing |  |  |  |
| IbL open | OFF | Opening Impulse lock | ON | The Start impulse has no effect during the opening phase. |  |  |  |
|  |  |  | OFF | The Start impulse becomes effective during the opening phase. |  |  |  |
| bL kch | OFF | Impulse lock TCA | ON | The Start impulse has no effect during the TCA dwell period. |  |  |  |
|  |  |  | OFF | The Start impulse becomes effective during the TCA dwell period. |  |  |  |
| $35 L E P$ | OFF | 3-step logic | ON | Enables 3-step logic. | A start impulse has the following effects: |  |  |
|  |  |  |  |  |  | 3 steps | 4 steps |
|  |  |  | OFF | Disables 3-step logic activating the 4-step logic. | closed | opens | opens |
|  |  |  |  |  | on closing |  | stop |
|  |  |  |  |  | open | closes | closes |
|  |  |  |  |  | on opening | stop + TCA | stop + TCA |
|  |  |  |  |  | after stop | opens | opens |
| PrE-RLRrit | OFF | Pre alarm | ON | The blinker comes on about 3 seconds before the motor starts. |  |  |  |
|  |  |  | OFF | The blinker comes on at the same time as the motor starts. |  |  |  |
| Phote. opEn | OFF | Photocells on opening | ON | In case of obscuring, this excludes photocell operation on opening. During the closing phase, immediately reverses the motion. |  |  |  |
|  |  |  | OFF | In case of obscuring, the photocells are active both on opening and on closing. When a pho tocell is obscured on closing, it reverses the motion only after the photocell is disengaged. |  |  |  |
| FR5t cL5 | OFF | Rapid closing | ON | Closes 3s after the photocells are cleared before waiting for the set TCA to elapse. |  |  |  |
|  |  |  | OFF | Command not entered. |  |  |  |
| tE5t Phot | OFF | Photocell test | ON | Activates photocell check (Fig. J) |  |  |  |
|  |  |  | OFF | Deactivates photocell check |  |  |  |
| tESt bRr | OFF | Electric edge test | ON | Activates electric edge check (Fig. J) |  |  |  |
|  |  |  | OFF | Deactivates electric edge check |  |  |  |
| F HEd codE | OFF | Fixed code | ON | The receiver is configured for operation in fixed-code mode, see paragraph on "Radio Transmitter Cloning". |  |  |  |
|  |  |  | OFF | The receiver is configured for operation in rolling-code mode, see paragraph on "Radio Transmitter Cloning". |  |  |  |
| rid o Proul | ON | Radio transmitter programming | ON | This enables transmitter storage via radio: <br> 1 - First press the hidden key and then the normal key (T1,T2,T3 orT4) of a transmitter already memorised in standard mode by means of the radio menu. <br> 2 - Within 10s press the hidden key and the normal key (T1, $\mathrm{T} 2, \mathrm{~T} 3$ or T 4 ) of a transmitter to be memorised. <br> The receiver exits the programming mode after 10s, other new transmitters can be entered before the end of this time. <br> This mode does not require access to the control panel. <br> IMPORTANT: Enables the automatic addition of new transmitters, clones and replays. |  |  |  |
|  |  |  | OFF | This disables transmitter storage via radio. The transmitters can only be memorised using the appropriate Radio menu. IMPORTANT: Disables the automatic addition of new transmitters, clones and replays.. |  |  |  |
| 1 not. on | OFF | 1 Active Motor | ON | Only motor 2 activated (1 leaf). |  |  |  |
|  |  |  | OFF | Both motors are activated (2 leaves). |  |  |  |
| 5cr-2ch | OFF | Gate-open or 2nd radio channel warning light | ON | The output between terminals 21 and 22 is configured as Gate-open warning light, in this case the 2nd radio channel controls pedestrian opening. |  |  |  |
|  |  |  | OFF | The output between terminals 21 and 22 is configured as 2nd radio channel. |  |  |  |
| chRnius not. | OFF | Reversing motion | ON | Opens in the other direction depending on how motors are installed. (Fig. M) |  |  |  |
|  |  |  | OFF |  |  |  |  |  |
| $\begin{aligned} & \text { PrE55. 5uc } \\ & \text { (special dip 1*) } \end{aligned}$ | ON | Closing limit switch pressure | ON | To be used when a closing backstop is present. <br> This function activates leaf pressure on the backstop, without this being considered as an obstacle by the ampere-stop sensor. <br> Therefore the rod continues its stroke for another 2s, after intercepting the closing limit switch or as far as the backstop. This way, by slightly anticipating closing limit switch activation, the leaves will come to a perfect halt against the end stop plates (Fig. K Rif. A). |  |  |  |
|  |  |  | OFF | Movement is exclusively stopped by proceed to a precise setting of closing | sing limit sw mit switch act | activation, ion (Fig. K R | is case you must ). |

*Refer for universal handheld programmer.


## USER WARNINGS (GB)

WARNING! Important safety instructions. Carefully read and comply with the Warnings and Instructions that come with the product as improper use can cause injury to people and animals and damage to property. Keep the instructions for future reference and hand them on to any new users.
This product is meant to be used only for the purpose for which it was explicitly installed. Any other use constitutes improper use and, consequently, is hazardous. The manufacturer cannot be held liable for any damage as a result of improper, incorrect or unreasonable use.

## GENERAL SAFETY

Thank you for choosing this product. The Firm is confident that its performance will meet your operating needs.
This productmeets recognized technical standards and complies with safety provision when installed correctly by qualified, expert personnel (professional installer)
If installed and used correctly, the automated system will meet operating safety standards. Nonetheless, it is advisable to observe certain rules of behaviour so that accidental problems can be avoided:
-Keep adults, children and property out of range of the automated system especially while it is moving.
-Do not allow children to play or stand within range of the automated system
-This automated system is not meant for use by children or by people with impaired mental, physical or sensory capacities, or people who do not have suitable knowledge.
-Do not work near hinges or moving mechanical parts.
-Donothinder the leaf's movement and donot attempt to open the doormanually unless the actuator has been released with the relevant release knob.
Keep out of range of the motorized door or gate while they are moving
-Keep remote controls or other control devices out of reach of children in order to avoid the automated system being operated inadvertently.
-The manual release's activation could result in uncontrolled door movements if there are mechanical faults or loss of balance.
-When using roller shutter openers: keep an eye on the roller shutter while it is moving and keep people away until it has closed completely. Exercise care when activating the release, if such a device is fitted, as an open shutter could drop quickly in the event of wear or breakage.
-The breakage or wear of any mechanical parts of the door (operated part), such as cables, springs, supports, hinges, guides..., may generate a hazard. Have the system checked by qualified, expert personnel (professional installer) at regular intervals according to the instructions issued by the installer or manufacturer of the door.
-When cleaning the outside, always cut off mains power.
-Keep the photocells'optics and illuminating indicator devices clean. Check that no branches or shrubs interfere with the safety devices.
-Do not use the automated system if it is in need of repair. In the event the auto mated system breaks down or malfunctions, cut off mains power to the system; do not attempt to repair or perform any other work to rectify the fault yoursel and instead call in qualified, expert personnel (professional installer) to perform the necessary repairs or maintenance. To allow access, activate the emergency release (where fitted).
-If any part of the automated system requires direct work of any kind that is not contemplated herein, employ the services of qualified, expert personne (professional installer).
-At least once a year, have the automated system, and especially all safety devices, checked by qualified, expert personnel (professional installer) to make sure that it is undamaged and working properly.
-A record must be made of any installation, maintenance and repair work and the relevant documentation kept and made available to the user on request.

- Failure to comply with the above may result in hazardous situations.

Anything that is not explicitly provided for in the user guide is not allowed. The operator's proper operation can only be guaranteed if the instructions given herein are complied with. The Firm shall not be answerable for damage caused by failure to comply with the instructions featured herein.
While we will not alter the product's essential features, the Firm reserves the right, at any time, to make those changes deemed opportune to improve the product from a technical, design or commercial point of view, and will not be required to update this publication accordingly.

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